Barriers on Symmetric Cones

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Outline

Conic optimization and barriers

Conic optimization Logarithmically homogeneous barriers Geometric view on barriers

Symmetric cones and self-scaled barriers

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Symmetric cones Parallel extrinsic curvature

Conic programs

Definition

A regular convex cone $K\subset \mathbb{R}^n$ is a closed convex cone having nonempty interior and containing no lines.

The dual cone

$$K^* = \{ y \in \mathbb{R}_n \, | \, \langle x, y \rangle \ge 0 \quad \forall \ x \in K \}$$

of a regular convex cone K is also regular.

Definition

A conic program over a regular convex cone $K \subset \mathbb{R}^n$ is an optimization problem of the form

$$\min_{x\in \mathbf{K}} \langle c, x \rangle : \quad Ax = b.$$

every convex optimization problem can be written as a conic program

Geometric interpretation



the feasible set is the intersection of K with an affine subspace

$$\min_{x} \langle c', x \rangle : A'x + b' \in K$$

explicit parametrization

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Logarithmically homogeneous barriers

Definition (Nesterov, Nemirovski 1994)

Let $K \subset \mathbb{R}^n$ be a regular convex cone. A (self-concordant logarithmically homogeneous) barrier on K is a smooth function $F : K^o \to \mathbb{R}$ on the interior of K such that

- $F(\alpha x) = -\nu \log \alpha + F(x)$ (logarithmic homogeneity)
- $F''(x) \succ 0$ (convexity)
- $\lim_{x \to \partial K} F(x) = +\infty$ (boundary behaviour)
- ▶ $|F'''(x)[h, h, h]| \le 2(F''(x)[h, h])^{3/2}$ (self-concordance)

for all tangent vectors h at x.

The homogeneity parameter ν is called the barrier parameter.

Theorem (Nesterov, Nemirovski 1994)

Let $K \subset \mathbb{R}^n$ be a regular convex cone and $F : K^o \to \mathbb{R}$ a barrier on K with parameter ν . Then the Legendre transform F^* is a barrier on $-K^*$ with parameter ν .

- the map $x \mapsto F'(x)$ takes the level surfaces of F to the level surfaces of F^*
- the map x → -F'(x) is an isometry between K° and (K*)° with respect to the Hessian metrics defined by F", (F*)"

Interior-point methods

let $K \subset \mathbb{R}^n$ be a regular convex cone let $F : K^o \to \mathbb{R}$ be a barrier on Kconsider the conic program

$$\min_{x \in \mathbf{K}} \langle \mathbf{c}, x \rangle : \quad \mathbf{A}x = \mathbf{b}$$

for $\tau > 0$, solve instead the unconstrained problem

$$\min_{x\in\mathbb{R}^n} \tau\langle c,x\rangle + F(x): \quad Ax = b$$

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- unique minimizer $x^*(\tau) \in K^o$ for every $\tau > 0$
- solution depends continuously on τ (central path)
- $x^*(\tau) \to x^*$ as $\tau \to \infty$

path-following methods:

alternate Newton steps and increments of τ the smaller the barrier parameter ν , the faster we can increase τ safely

Second fundamental form

let $M \subset M$ be a submanifold of a (pseudo-)Riemannian space choose a point $x \in M$ and a tangent vector $h \in T_x M$

consider the geodesics γ_M, γ_M in M and in M through x with velocity h there is a second-order deviation

$$\gamma_{\mathcal{M}}(t) - \gamma_{\mathcal{M}}(t) = \left(\left. \frac{d^2}{dt^2} \right|_{t=0} (\gamma_{\mathcal{M}} - \gamma_{\mathcal{M}}) \right) \cdot \frac{t^2}{2} + O(t^3)$$

whose main term depends quadratically on h

the acceleration is called the second fundamental form II of M

 $II_x : T_x M \times T_x M \to (T_x M)^{\perp}$ $T_x M$ tangent subspace, $(T_x M)^{\perp}$ normal subspace



the second fundamental form measures the deviation of \boldsymbol{M} from a geodesic submanifold

it is also called the extrinsic curvature

Para-Kähler space

consider the product $E_{2n} = \mathbb{R}^n \times \mathbb{R}_n = \{u = (x, p) | x \in \mathbb{R}^n, p \in \mathbb{R}_n\}$

for a vector space, we may identify the space with the tangent spaces at its points

 E_{2n} carries natural structures:

- ▶ $||u||^2 = \langle x, p \rangle$ is a flat pseudo-Riemannian metric G with neutral signature
- $dx \wedge dp$ is a symplectic form ω , $\omega(u_1, u_2) = \frac{1}{2}(\langle x_1, p_2 \rangle \langle x_2, p_1 \rangle)$
- (x, p) → (x, -p) is an involution J whose eigenspaces define completely integrable distributions

these structures are compatible:

• $\hat{\nabla}\omega = 0$ ($\hat{\nabla}$ is the parallel transport of G)

•
$$Jg = \omega$$

 E_{2n} is a (the) flat para-Kähler space form

Barriers as Lagrangian submanifolds

duality $K \subset \mathbb{R}^n \leftrightarrow K^* \subset \mathbb{R}_n, x \leftrightarrow p = -F'(x)$

to a barrier F on a cone K associate the submanifold

$$M = \{(x, p) \in E_{2n} | x \in K^{\circ}, \ p = -F'(x)\}$$

the structures defined by F on K° have a natural explanation in terms of the structures defined by E_{2n} on its submanifold M

- the metric g = F'' on K^o is ν times the submanifold metric on M, $g = \nu \cdot G|_M$
- *M* is a non-degenerate definite Lagrangian submanifold, $\omega|_M = 0$
- J is a bijection between the tangent and the normal subspaces to M

$$\blacktriangleright F''' = \omega \cdot II = Jg \cdot II$$

Theorem

The self-concordance condition on F is equivalent to the boundedness of the extrinsic curvature of M. The barrier parameter ν measures the supremum of the norm of the extrinsic curvature.

- \triangleright ν bounds the deviation of M from a totally geodesic submanifold of E_{2n}
- geodesic submanifolds of E_{2n} correspond to quadratic functions

Symmetric cones

Definition

A self-dual, homogeneous convex cone is called symmetric.

- ▶ self-dual: $K = K^*$
- homogeneous: Aut K acts transitively on K^o

conic programs over symmetric cones are efficiently solvable by interior-point methods due to the existence of self-scaled barriers [Nesterov, Nemirovski, 1994]

- linear programs (LP) over $\mathbb{R}^n_+ \sim 10^6$ variables
- conic quadratic programs (CQP) over $L_n \sim 10^4$ variables
- semi-definite programs (SDP) over $S_+(n) \sim 10^2$ variables

structure can greatly increase tractable sizes

free (CLP, LiPS, SDPT3, SeDuMi, ...) and commercial (CPLEX, MOSEK, ...) solvers available

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Self-scaled barriers on symmetric cones

Theorem (Vinberg, 1960; Koecher, 1962)

Every symmetric cone can be represented as a direct product of a finite number of the following irreducible symmetric cones:

- Lorentz (or second order) cone $L_n = \left\{ (x_0, \dots, x_{n-1}) \mid x_0 \ge \sqrt{x_1^2 + \dots + x_{n-1}^2} \right\}$
- matrix cones S₊(n), H₊(n), Q₊(n) of real, complex, or quaternionic hermitian positive semi-definite matrices
- Albert cone $O_+(3)$ of octonionic hermitian positive semi-definite 3×3 matrices

barriers on irreducible symmetric cones

- Lorentz cone L_n : $F(x) = -\log(x_0^2 x_1^2 \dots x_{n-1}^2)$
- ▶ matrix cones: F(X) = − log det X

barriers on reducible symmetric cones weighted sums of the barriers on the irreducible components

example:
$$K = \mathbb{R}^n_+$$
, $F(x) = -\sum_{k=1}^n lpha_k \log x_k$, $lpha_k \ge 1$

Main result

Theorem

Let $K \subset \mathbb{R}^n$ be a regular convex cone, and let $F : K^o \to \mathbb{R}^n$ be a convex, logarithmically homogeneous function such that $\lim_{x\to\partial K} F(x) = +\infty$. Then the following are equivalent:

- K is a symmetric cone and F a self-scaled barrier,
- the product of the inversion J with the extrinsic curvature of the submanifold $M \subset E_{2n}$ is parallel with respect to the geodesic flow on K° ,
- the derivative F''' is parallel with respect to the geodesic flow on K° , $\hat{\nabla}F''' = 0$.

a barrier is self-scaled if and only if the acceleration of the geodesics on M is invariant with respect to the geodesic flow on M

the barrier F behaves in some precise sense as a primal-dual 3rd order polynomial: it is the mean between the cases when F is cubic and when F^* is cubic

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the parallelism condition is local

Explicit equation

we note
$$\frac{\partial F}{\partial x^{\alpha}} = F_{,\alpha}$$
, $\frac{\partial^2 F}{\partial x^{\alpha} \partial x^{\beta}} = F_{,\alpha\beta}$ etc.
note $F^{,\alpha\beta}$ for the inverse of the Hessian

we adopt the Einstein summation convention over repeating indices, e.g.,

$$F^{,lphaeta}F_{,eta\gamma}:=\sum_{eta=1}^nF^{,lphaeta}F_{,eta\gamma}=\delta^lpha_\gamma$$

then $\hat{\nabla}F^{\prime\prime\prime\prime}=0$ is equivalent to the 4-th order quasi-linear PDE

$$F_{,\alpha\beta\gamma\delta} = \frac{1}{2} F^{,\rho\sigma} \left(F_{,\alpha\beta\rho} F_{,\gamma\delta\sigma} + F_{,\alpha\gamma\rho} F_{,\beta\delta\sigma} + F_{,\alpha\delta\rho} F_{,\beta\gamma\sigma} \right)$$

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F is self-scaled if and only if it is a solution to this PDE

a solution can be recovered from the values of F, F', F'', F''' at a single point

Idea of proof

differentiating with respect to x^η and substituting the fourth order derivatives by the right-hand side, we get

$$\begin{split} F_{,\alpha\beta\gamma\delta\eta} &= \frac{1}{4} F^{,\rho\sigma} F^{,\mu\nu} \left(F_{,\beta\eta\nu} F_{,\alpha\rho\mu} F_{,\gamma\delta\sigma} + F_{,\alpha\eta\mu} F_{,\rho\beta\nu} F_{,\gamma\delta\sigma} \right. \\ &+ F_{,\gamma\eta\nu} F_{,\alpha\rho\mu} F_{,\beta\delta\sigma} + F_{,\alpha\eta\mu} F_{,\rho\gamma\nu} F_{,\beta\delta\sigma} + F_{,\beta\eta\nu} F_{,\gamma\rho\mu} F_{,\alpha\delta\sigma} \\ &+ F_{,\gamma\eta\mu} F_{,\rho\beta\nu} F_{,\alpha\delta\sigma} + F_{,\beta\eta\nu} F_{,\delta\rho\mu} F_{,\alpha\gamma\sigma} + F_{,\delta\eta\mu} F_{,\rho\beta\nu} F_{,\alpha\gamma\sigma} \\ &+ F_{,\delta\eta\nu} F_{,\alpha\rho\mu} F_{,\beta\gamma\sigma} + F_{,\alpha\eta\mu} F_{,\rho\delta\nu} F_{,\beta\gamma\sigma} + F_{,\delta\eta\nu} F_{,\gamma\rho\mu} F_{,\alpha\beta\sigma} \\ &+ F_{,\gamma\eta\mu} F_{,\rho\delta\nu} F_{,\alpha\beta\sigma} \Big) \end{split}$$

anti-commuting δ, η gives the integrability condition

$$\begin{split} F^{,\rho\sigma}F^{,\mu\nu}\left(F_{,\beta\eta\nu}F_{,\delta\rho\mu}F_{,\alpha\gamma\sigma}+F_{,\alpha\eta\mu}F_{,\rho\delta\nu}F_{,\beta\gamma\sigma}+F_{,\gamma\eta\mu}F_{,\rho\delta\nu}F_{,\alpha\beta\sigma}\right.\\ \left.-F_{,\beta\delta\nu}F_{,\eta\rho\mu}F_{,\alpha\gamma\sigma}-F_{,\alpha\delta\mu}F_{,\rho\eta\nu}F_{,\beta\gamma\sigma}-F_{,\gamma\delta\mu}F_{,\rho\eta\nu}F_{,\alpha\beta\sigma}\right)=0. \end{split}$$

define a multiplication on the tangent space by

$$(u \bullet v)^{\alpha} = \frac{1}{2} F^{,\alpha\delta} F_{,\delta\beta\gamma} u^{\beta} v^{\gamma}$$

this defines a commutative algebra satisfying the Jordan identity

$$(u^2 \bullet v) \bullet u = (u \bullet v) \bullet u^2$$

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connection between Jordan algebras and symmetric cones is long known

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Thank you

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