## Semidefinite Representations of Sets Delineated by Plane Quartics

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- Semi-algebraic sets
- Semi-definite representations
- 2 Representation of planar quartic sets
  - Planar sets and their homogenizations
  - Lasserre construction and its homogenization
  - Representation of planar quartic sets

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#### Semi-definite representability

- Semi-algebraic sets
- Semi-definite representations

#### 2 Representation of planar quartic sets

- Planar sets and their homogenizations
- Lasserre construction and its homogenization
- Representation of planar quartic sets

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Semi-algebraic sets Semi-definite representations

## Semi-algebraic sets

#### Definition

A subset

$$S = \{x \in \mathbb{R}^n | p_k(x) = 0, k = 1, ..., m; q_l(x) > 0, l = 1, ..., m'\}$$

given by a finite number of polynomial equalities and inequalities is called basic semi-algebraic.

#### Definition

A set  $S \subset \mathbb{R}^n$  which is a finite union of basic-semi-algebraic sets is called semi-algebraic.

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Semi-algebraic sets Semi-definite representations

## Conic semi-algebraic sets

#### Lemma

Let  $S \subset \mathbb{R}^n$  be a semi-algebraic set. Then the set

$$ilde{\mathbf{S}} = \{ ilde{\mathbf{x}} = (\lambda, \lambda \mathbf{x}^{\mathcal{T}})^{\mathcal{T}} \, | \, \lambda \geq \mathbf{0}, \; \mathbf{x} \in \mathbf{S}\} \subset \mathbb{R}^{n+1}$$

is also semi-algebraic.

- homogenize polynomials
- add constraint  $x_0 > 0$
- unite with {0}

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## Semi-definite representability

#### Definition

A cone *K* is called **semi-definite representable** if it is linearly isomorphic to a linear projection of a linear section of  $S_+(n)$  for some *n*.

- linear intersection with subspace  $L \subset S(n)$
- linear projection along subspace  $L' \subset L$

assume  $L \cap S_{++}(n) \neq \emptyset$ 

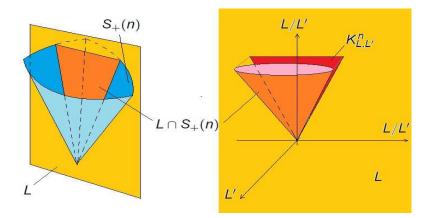
K linearly isomorphic to

$$\mathcal{K}^n_{L,L'} = \{ \mathbf{x} \in L/L' \mid \exists \mathbf{y} \in \mathbf{x} : \mathbf{y} \in L \cap S_+(n) \}$$

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## Semi-definite representable cones



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## Example

#### Nonnegative ternary quartics [Hilbert, 1888]:

$$\sum_{lpha+eta\leq 4} oldsymbol{c}_{lphaeta} oldsymbol{x}^{lpha} oldsymbol{y}^{eta} \geq oldsymbol{0} \quad orall oldsymbol{x}, oldsymbol{y} \in \mathbb{R}$$

 $\Leftrightarrow \qquad \exists a_{02}, a_{20}, a_{22}, a_{21}, a_{12}, a_{11} \in \mathbb{R}:$ 

 $\begin{pmatrix} 2c_{40} & c_{22} - a_{22} & c_{20} - a_{20} & c_{21} - a_{21} & c_{30} & c_{31} \\ c_{22} - a_{22} & 2c_{04} & c_{02} - a_{02} & c_{03} & c_{12} - a_{12} & c_{13} \\ c_{20} - a_{20} & c_{02} - a_{02} & 2c_{00} & c_{01} & c_{10} & c_{11} - a_{11} \\ c_{21} - a_{21} & c_{03} & c_{01} & 2a_{02} & a_{11} & a_{12} \\ c_{30} & c_{12} - a_{12} & c_{10} & a_{11} & 2a_{20} & a_{21} \\ c_{31} & c_{13} & c_{11} - a_{11} & a_{12} & a_{21} & 2a_{22} \end{pmatrix} \succeq 0$ 

n = 6, dim  $L = \dim S(6) = 21$ , dim L' = 6, dim  $K = \dim L/L' = 15$ 

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## Duality

#### Definition

Let  $K \subset \mathbb{R}^n$  be a convex cone. The dual cone to K is given by

$$\mathbf{K}^* = \{\mathbf{y} \in \mathbb{R}_n \,|\, \langle \mathbf{x}, \mathbf{y} 
angle \geq \mathbf{0} \quad \forall \; \mathbf{x} \in \mathbf{K} \}.$$

#### Theorem

Let  $L' \subset L \subset S(n)$  be linear subspaces,  $L \cap S_{++}(n) \neq \emptyset$ . Then

$$(K_{L,L'}^n)^* = K_{L'^{\perp},L^{\perp}}^n$$

Here  $L'^{\perp}$ ,  $L^{\perp}$  are the orthogonal complements of L', L.

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## **Problem formulation**

necessary conditions for semi-definite representability of K

- K is convex
- K is semi-algebraic

## Is every regular convex semi-algebraic cone semi-definite representable?

this talk

- dim *K* = 3
- defining polynomials are quartics

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## Known results

- semi-definite representability local property of the boundary [Helton, Nie 2009]
- smooth boundary patches with positive curvature are not an obstacle [Helton, Nie 2010]
- more explicit construction in [Nie, 2010] with convexity assumptions on the defining polynomials
- the semi-definite representation is a member of the Lasserre hierarchy [Lasserre, 2009]
- degree of the LMI can be arbitrarily high

[Henrion, 2009]: semi-definite representation of convex hulls of certain rational algebraic varieties and of zero sets of convex polynomials with fixed block size

### Planar semi-algebraic sets

#### Lemma

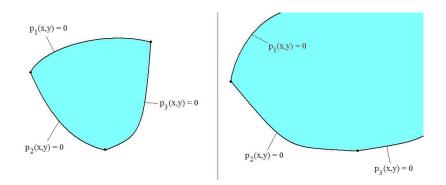
A closed convex semi-algebraic set  $S \subset \mathbb{R}^2$  is bounded by a finite number of arcs. The Zariski closure of each arc is a plane algebraic curve, which is the zero set of some nonzero irreducible polynomial.

#### w.r.o.g.

- the interior of each arc consists of nonsingular points
- in the interior of each arc the curvature is nonzero
- defining polynomials are positive on the inside of S

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#### Compact and noncompact case



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## Homogenization

#### Lemma

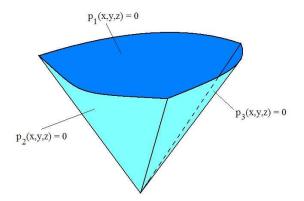
A regular convex semi-algebraic cone  $K \subset \mathbb{R}^3$  is bounded by a finite number of conic surface patches. The Zariski closure of each patch corresponds to a plane projective algebraic curve, which is the zero set of some nonzero irreducible polynomial.

#### w.r.o.g.

- the interior of each patch consists of nonsingular points
- in the interior of each patch the curvature is nonzero
- defining polynomials are positive on the inside of K

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#### 3-dimensional cones



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## **Regularity condition**

 $\Delta \subset \partial S$  — boundary patch defined by p(x, y, z) = 0 $v^* = (x^*, y^*, z^*) \in \Delta^o$  — interior point

 $v^*$  nonsingular:  $p'(v^*) \neq 0$ 

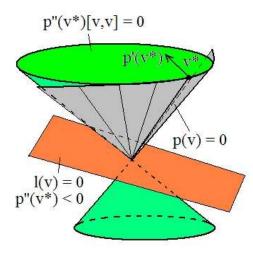
curvature at  $v^*$  nonzero:  $p''(v^*) < 0$  on the direction  $v^* \times p'(v^*) \Leftrightarrow \det p''(v^*) > 0$ 

 $p''(v^*)$  of signature (+--)

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## Local geometry of $p''(v^*)$



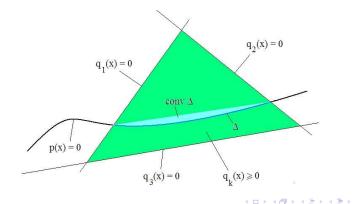
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#### **Problem formulation**

describe by LMI's the convex hull of the set

 $\Delta = \{ x \in \mathbb{R}^n \, | \, p(x) = 0, \, q_k(x) \ge 0, \, k = 1, \dots, m \}$ 



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#### Moment vectors

#### Definition

For  $x \in \mathbb{R}^n$ , let  $\mathcal{X}_N(x)$  be the vector of monomials  $x^{\alpha}$  with  $|\alpha| \leq N$ .

the PSD rank 1 matrix  $\mathcal{X}_N(x)\mathcal{X}_N^T(x)$  contains the elements of  $\mathcal{X}_{2N}(x)$ 

 $\Rightarrow$  the vector  $\mathcal{X}_{2N}(x)$  has to satisfy the corresponding LMI

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#### LMI constraints on moment vectors

$$\Delta = \{ x \in \mathbb{R}^n \, | \, p(x) = 0, \, q_k(x) \ge 0, \, k = 1, \dots, m \}$$

for every  $x \in \Delta$ ,  $N \in \mathbb{N}$  sufficiently large,  $\mathcal{X}_{2N}(x)$  satisfies the linear constraint

$$p(x)b(x)=0$$

for every polynomial *b* with deg  $b + \text{deg } p \le 2N$ 

for every  $I \subset \{1, \ldots, m\}$ ,  $\mathcal{X}_{2N}(x)$  satisfies the LMI

$$\prod_{k\in I} q_k(x) \mathcal{X}_{N'}(x) \mathcal{X}_{N'}^T(x) \succeq 0$$

with  $N' \leq N - \frac{1}{2} \sum_{k \in I} \deg q_k$ 

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## Recovery of the original point

suppose we have a semi-definite representable set S in moment space

the map  $\Pi : \mathcal{X}_{2N}(x) \mapsto x$  is a linear projection

#### Lemma

Let  $\Delta \subset \mathbb{R}^n$  be a set and

$$S \supset \{\mathcal{X}_{2N}(x) \mid x \in \Delta\}$$

a convex outer approximation of the corresponding moment set. Then  $\Pi[S]$  is an outer approximation of conv $\Delta$ .

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## Scheme of relaxation

# $\{\mathcal{X}_{2N}(\boldsymbol{x}) \,|\, \boldsymbol{x} \in \Delta\} \subset S$ $\Pi \downarrow \qquad \Pi \downarrow$ $\Delta \qquad \subset \Pi[S]$

- S defined by LMIs which  $\mathcal{X}_{2N}(x)$  satisfy
- S, Π[S] semi-definite representable
- $\Pi[S]$  is the Lasserre relaxation of conv  $\Delta$

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#### Homogeneous moments

#### Definition

For  $x \in \mathbb{R}^{n+1}$ , let  $\mathcal{X}_N(x)$  be the vector of monomials  $x^{\alpha}$  with  $|\alpha|=N$ .

the PSD rank 1 matrix  $\mathcal{X}_N(x)\mathcal{X}_N^T(x)$  contains the elements of  $\mathcal{X}_{2N}(x)$ 

⇒ the vector  $\mathcal{X}_{2N}(x)$  has to satisfy the corresponding LMI other LMIs carry over from inhomogeneous case

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## Recovery of the original point

the linear projection  $\Pi : \mathcal{X}_{2N}(x) \mapsto x$  is no longer available

- choose polynomial f(x) of degree 2N 1
- define linear projection  $\Pi : \mathcal{X}_{2N}(x) \mapsto (f(x)x_k)_{k=0,...,n}$

 $x \mapsto \mathcal{X}_{2N}(x) \mapsto f(x) \cdot x$  is "pointwise homothety"

recovery of original point up to scalar factor f(x)

does not matter since we are in homogeneous setting

## Recovery cont'd

#### Lemma

Let  $\Delta \subset \mathbb{R}^{n+1}$  be a conic set and

 $S \supset \{\mathcal{X}_{2N}(\textbf{\textit{x}}) \,|\, \textbf{\textit{x}} \in \Delta\}$ 

a closed convex outer approximation of the moment set. Let f of degree 2N - 1 be such that f(x) > 0 a.e. on  $\Delta$ . Then  $K = \Pi[S]$  is an outer approximation of conv  $\Delta$ .

many degrees of freedom to construct relaxations

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#### Form of relaxation parameters

*p* defining boundary patch  $\Delta$  is a quartic polynomial

- $N = 2 \Rightarrow$  monomials up to 4th order
- q isolating  $\Delta$  is a quadric with signature (+ -)
- f defining the recovering projection  $\Pi$  is  $I^3$

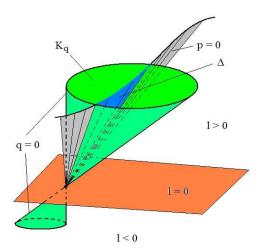
*I* linear functional s.t.  $q \prec 0$ ,  $p''(v) \prec 0$  on ker *I* for all  $v \in \Delta$ 

$$\Delta = \{ v = (x, y, z) \, | \, p(v) = 0, \, q(v) \ge 0, \, l(v) \ge 0 \}$$

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#### Geometric interpretation



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## **Explicit description**

$$\Sigma = S^* = \{ p \cdot b + \sigma_1 q + \sigma_2 \, | \, b \in \mathbb{R}, \, \sigma_1, \sigma_2 \text{ SOS} \}$$

is dual to the cone of moment vectors satisfying the LMI  $\sigma_1, \sigma_2$  SOS of degree 2,4  $\Leftrightarrow \sigma_1 \ge 0, \sigma_2 \ge 0$ 

$$\textit{K}^{*} = (\Pi[\textit{S}])^{*} = \{\textit{y} \in \mathbb{R}_{n} \, | \, \textit{I}^{3} \cdot \textit{y}(\cdot) \in \Sigma\}$$

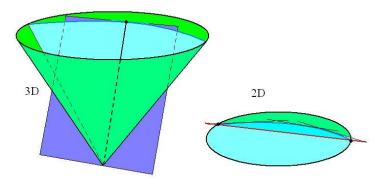
is the dual to the convex cone K approximating conv  $\Delta$ 

linear functionals y such that  $l^3y \in \Sigma$  are supporting the semi-definite approximation K

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## Supporting planes

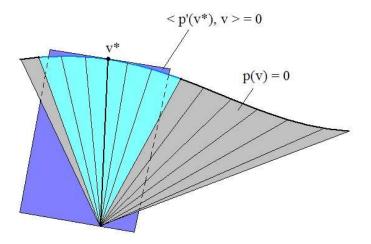


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#### **Gradient functional**



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#### Reduction to polynomial inequality

to show: 
$$l^3 \cdot \langle p'(v^*), \cdot \rangle = p \cdot b + \sigma_1 \cdot q + \sigma_2, \ b \in \mathbb{R}, \sigma_1, \sigma_2 \ge 0$$

let  $v^0$  be the centre of  $\Delta$  normalized s.t.  $I(v^0) = 1$ 

with c > 0 set

• 
$$b = l^{3}(v^{*})$$
  
•  $q = \varepsilon^{2}l^{2}(v) + p''(v^{0})[v - l(v)v^{0}, v - l(v)v^{0}]$   
•  $\sigma_{1} = -c \cdot l(v^{*}) \cdot p''(v^{0})[l(v^{*})v - l(v)v^{*}, l(v^{*})v - l(v)v^{*}]$ 

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#### Reduction to polynomial inequality

to show: 
$$l^3 \cdot \langle p'(v^*), \cdot \rangle = p \cdot b + \sigma_1 \cdot q + \sigma_2, \ b \in \mathbb{R}, \sigma_1, \sigma_2 \ge 0$$
  
set  $b = l^3(v^*)$ , for  $v^0$  with  $l(v^0) = 1$   
 $q = \varepsilon^2 l^2(v) + p''(v^0)[v - l(v)v^0, v - l(v)v^0],$   
 $\sigma_1 = -c \cdot l(v^*) \cdot p''(v^0)[l(v^*)v - l(v)v^*, l(v^*)v - l(v)v^*], c > 0$ 

sufficient condition: for all  $v \in \mathbb{R}^3$  and all  $v^* \in K_q$ 

$$I(v^*)\left[I^3(v)\cdot\langle p'(v^*),v\rangle-p(v)\cdot b-\sigma_1\cdot q\right]-3I^4(v)\cdot p(v^*)\geq 0$$

homogeneous in each of  $v, v^*$  of degree 4

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#### Reduction to polynomial inequality

to show: 
$$l^3 \cdot \langle p'(v^*), \cdot \rangle = p \cdot b + \sigma_1 \cdot q + \sigma_2, \ b \in \mathbb{R}, \sigma_1, \sigma_2 \ge 0$$
  
set  $b = l^3(v^*)$ , for  $v^0$  with  $l(v^0) = 1$   
 $q = \varepsilon^2 l^2(v) + p''(v^0)[v - l(v)v^0, v - l(v)v^0],$   
 $\sigma_1 = -c \cdot l(v^*) \cdot p''(v^0)[l(v^*)v - l(v)v^*, l(v^*)v - l(v)v^*], c > 0$ 

sufficient condition: for all  $v \in \mathbb{R}^3$  and all  $v^* \in K_q$ 

$$I(v^*)\left[I^3(v)\cdot\langle p'(v^*),v\rangle-p(v)\cdot b-\sigma_1\cdot q\right]-3I^4(v)\cdot p(v^*)\geq 0$$

homogeneous in each of  $v, v^*$  of degree 4

for 
$$l(v^*) = l(v) = 1$$
:  
 $c\left(\varepsilon^2 + p''(v^0)[v - v^0, v - v^0]\right) \le \frac{p(v) - p(v^*) - \langle p'(v^*), v - v^* \rangle}{p''(v^0)[v - v^*, v - v^*]}$ 

#### Polar coordinates

pass to polar coordinates in ker / with scalar product  $-p''(v^0)$ 

with 
$$v - v^* = \delta \begin{pmatrix} \cos \zeta \\ \sin \zeta \end{pmatrix}$$
,  $v^* - v^0 = \rho \begin{pmatrix} \cos \xi \\ \sin \xi \end{pmatrix}$   
 $c \left( \varepsilon^2 + p''(v^0) [v - v^0, v - v^0] \right) =$   
 $= c \left( \varepsilon^2 - ||v - v^0||^2 \right) \le c \left( \varepsilon^2 - (\delta - \rho)^2 \right)$   
 $\frac{p(v) - p(v^*) - \langle p'(v^*), v - v^* \rangle}{p''(v^0) [v - v^*, v - v^*]} =$   
 $= -\frac{\frac{1}{2} p''(v^*) [v - v^*] + \frac{1}{6} p'''(v^*) [v - v^*] + \frac{1}{24} p'^V [v - v^*]}{\delta^2}$   
 $= \frac{1}{2} + \sum_{1 \le k+l \le 2} c_{kl}(\zeta, \xi) \delta^k \rho^l \ge \frac{1}{2} + \sum_{1 \le k+l \le 2} \min_{\zeta, \xi} c_{kl} \delta^k \rho^l$ 

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#### Reduction to copositivity condition

with 
$$\tilde{c}_{kl} = \min_{\zeta,\xi} c_{kl}$$
:

$$\mathsf{c}\left(arepsilon^2-(\delta-
ho)^2
ight)\leq rac{1}{2}+\sum_{1\leq k+l\leq 2} ilde{\mathsf{c}}_{kl}\delta^k
ho^l$$

for all  $\delta = ||\mathbf{v} - \mathbf{v}^*|| \in \mathbb{R}_+$ ,  $\rho = ||\mathbf{v}^* - \mathbf{v}^0|| \in [\mathbf{0}, \varepsilon]$ 

$$\begin{pmatrix} \frac{1}{2} - c\varepsilon^2 & \frac{\tilde{c}_{10}}{2} & \frac{1}{2} + \varepsilon \frac{\tilde{c}_{01}}{2} - c\varepsilon^2 \\ \frac{\tilde{c}_{10}}{2} & \tilde{c}_{20} + c & \frac{\tilde{c}_{10}}{2} + \varepsilon \frac{\tilde{c}_{11}}{2} - \varepsilon c \\ \frac{1}{2} + \varepsilon \frac{\tilde{c}_{01}}{2} - c\varepsilon^2 & \frac{\tilde{c}_{10}}{2} + \varepsilon \frac{\tilde{c}_{11}}{2} - \varepsilon c & \frac{1}{2} + \varepsilon \tilde{c}_{01} + \varepsilon^2 \tilde{c}_{02} \end{pmatrix} \in \mathcal{C}_3$$

 $\Leftrightarrow$ 

satisfied if c large and  $\varepsilon$  small

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Main result

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#### Theorem

Let p be a homogeneous ternary quartic, let Z(p) be the zero set of p, and let  $v^0 \in Z(p)$  be a regular point such that det  $p''(v^*) > 0$ . Then there exists a conic subset  $\Delta \subset Z(p)$  containing  $v^0$  in its interior such that conv  $\Delta$  has a semi-definite description with blocks of size 1,3 and 6 and with 11 lifting variables.

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# Thank you

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